

Ambient Light Sensor IC Series

Digital 16bit Serial Output Type

Ambient Light Sensor IC

BH1710FVC



● Descriptions

BH1710FVC is a digital Ambient Light Sensor IC for I²C bus interface. This IC is the most suitable to obtain the ambient light data for adjusting LCD and Keypad backlight power of Mobile phone. It is possible to detect wide range at High resolution. (1 - 65535 lx).

● Features

- 1) I²C bus Interface (f / s Mode Support)
- 2) Spectral responsibility is approximately human eye response
- 3) Illuminance to Digital Converter
- 4) Wide range and High resolution. (1 – 65535 lx)
- 5) Low Current by power down function
- 6) 50Hz / 60Hz Light noise reject-function
- 7) 1.8V Logic input interface
- 8) No need any external parts
- 9) Light source dependency is little. (ex. Incandescent Lamp. Fluorescent Lamp. Halogen Lamp. White LED. Sun Light)
- 10) It is possible to select 2 type of I²C slave-address.
- 11) Adjustable measurement result for influence of optical window (It is possible to detect min. 0.35 lx, max. 100000 lx by using this function.)

● Applications

Mobile phone, LCD TV, NOTE PC, Portable game machine, Digital camera, Digital video camera, Car navigation, PDA, LCD display

● Absolute Maximum Ratings

Parameter	Symbol	Limits	Units
Supply Voltage	Vmax	4.5	V
Operating Temperature	Topr	-30~85	°C
Storage Temperature	Tstg	-40~100	°C
SDA Sink Current	I _{max}	7	mA
Power Dissipation	Pd	260 _※	mW

※ 70mm × 70mm × 1.6mm glass epoxy board. Derating in done at 3.47mW/°C for operating above Ta=25°C.

● Operating Conditions

Parameter	Symbol	Min.	Typ.	Max.	Units
VCC Voltage	Vcc	2.4	3.0	3.6	V
I ² C Reference Voltage	VDVI	1.65	—	VCC	V

● Electrical Characteristics (VCC = 3.0V, DVI = 3.0V, Ta = 25°C, unless otherwise noted)

Parameter	Symbol	Min.	Typ.	Max.	Units	Conditions
Supply Current	Icc1	—	120	190	uA	Ev = 100 lx ※1
Powerdown Current	Icc2	—	0.01	0.2	uA	No input Light
Peak Wave Length	λ p	—	560	—	nm	
Measurement Accuracy	S/A	0.75	1.2	1.65	times	Sensor out / Actual lx EV = 1000 lx ※1, ※2
Dark (0 lx) Sensor out	S0	0	0	2	count	H-Resolution Mode ※3
H-Resolution Mode Resolution	rHR	—	1	—	lx	
M-Resolution Mode Resolution	rMR	—	4	—	lx	
L-Resosution Mode Resolution	rLR	—	32	—	lx	
H-Resolution Mode Measurement Time	tHR	—	120	180	ms	
M-Resolution Mode Measurement Time	tMR	—	16	24	ms	
L-Resolution Mode Measurementt time	tLR	—	2.9	4.5	ms	
Incandescent / Fluorescent Sensor out ratio	rIF	—	1	—	times	EV = 1000 lx
ADDR Input 'H' Voltage	VAH	0.7 * VCC	—	—	V	
ADDR Input 'L' Voltage	VAL	—	—	0.3 * VCC	V	
DVI Input 'L' Voltage	VDVL	—	—	0.4	V	
SCL, SDA Input 'H' Voltage 1	VIH1	0.7 * DVI	—	—	V	DVI ≥ 1.8V
SCL, SDA Input 'H' Voltage 2	VIH2	1.26	—	—	V	1.65V ≤ DVI < 1.8V
SCL, SDA Input 'L' Voltage 1	VIL1	—	—	0.3 * DVI	V	DVI ≥ 1.8V
SCL, SDA Input 'L' Voltage 2	VIL2	—	—	DVI – 1.26	V	1.65V ≤ DVI < 1.8V
SCL, SDA, ADDR Input 'H' Current	IiH	—	—	10	uA	
SCL, SDA, ADDR Input 'L' Current	IiL	—	—	10	uA	
I ² C SDA Output 'L' Voltage	VOL	0	—	0.4	V	IOL = 3 mA
I ² C SCL Clock Frequency	fSCL	—	—	400	kHz	
I ² C Hold Time (repeated) START Condition	tHDSTA	0.6	—	—	us	
I ² C 'L' Period of the SCL Clock	tLOW	1.3	—	—	us	
I ² C 'H' Period of the SCL Clock	tHIGH	0.6	—	—	us	
I ² C Set up time for a Repeated START Condition	tSUSTA	0.6	—	—	us	
I ² C Data Hold Time	tHDDAT	0	—	0.9	us	
I ² C Data Setup Time	tSUDAT	100	—	—	ns	
I ² C Set up Time for STOP Condition	tSUSTO	0.6	—	—	us	
I ² C Bus Free Time between a STOP and START Condition	tBUF	1.3	—	—	us	

※1 White LED is used as optical source.

※2 Measurement Accuracy typical value is possible to change '1' by "Measurement result adjustment function".

※3 Use H-Resolution Mode if dark data (less than 10 lx) is need.

● Reference Data

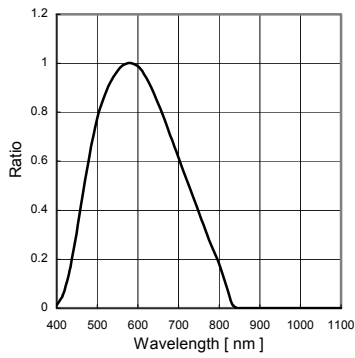


Fig.1 Spectral Response

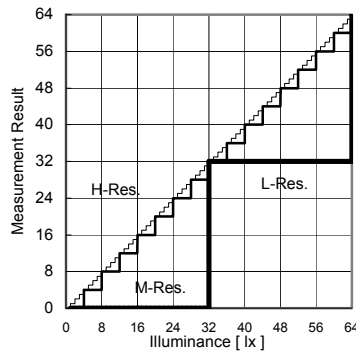


Fig.2 Illuminance – Measurement Result 1

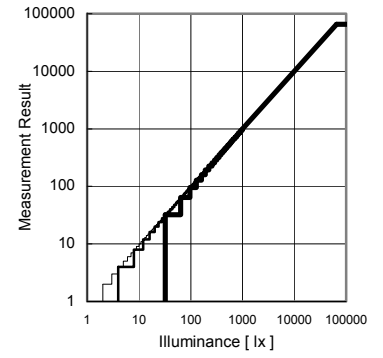


Fig.3 Illuminance – Measurement Result 2

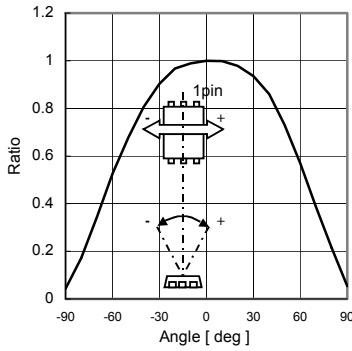


Fig.4 Directional Characteristics 1

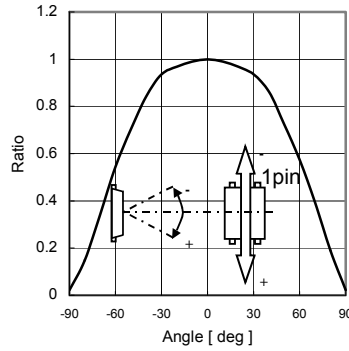


Fig.5 Directional Characteristics 2

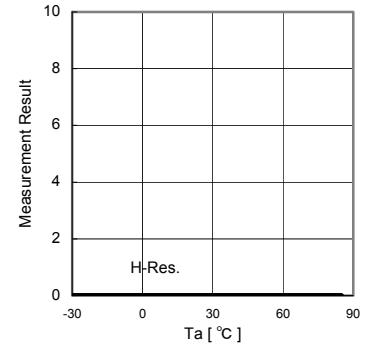


Fig.6 Dark Response

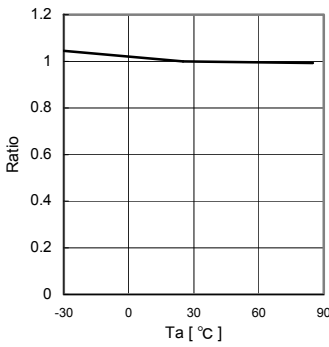


Fig.7 Measurement Result Temperature Dependency

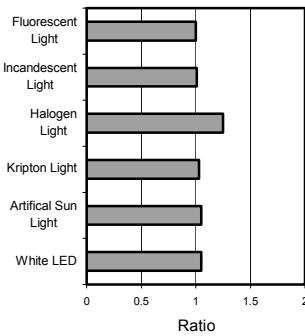


Fig.8 Light Source Dependency (Fluorescent Light is set to '1')

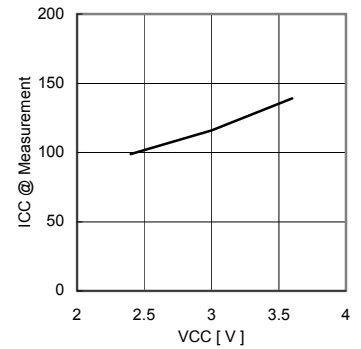


Fig.9 VCC – ICC (During measurement)

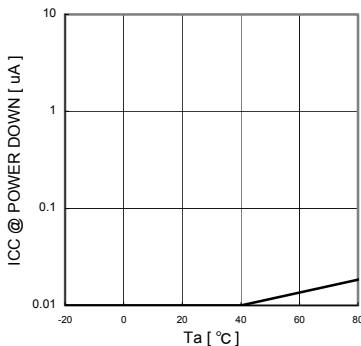


Fig.10 VCC – ICC@0 Lx (POWER DOWN)

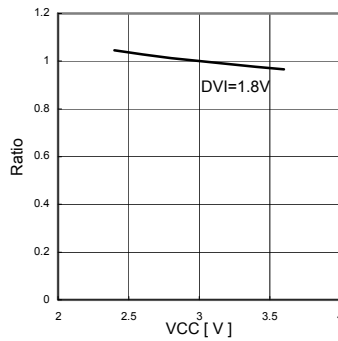


Fig.11 Measurement Result VCC Dependency

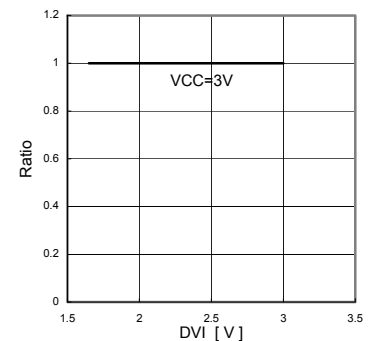
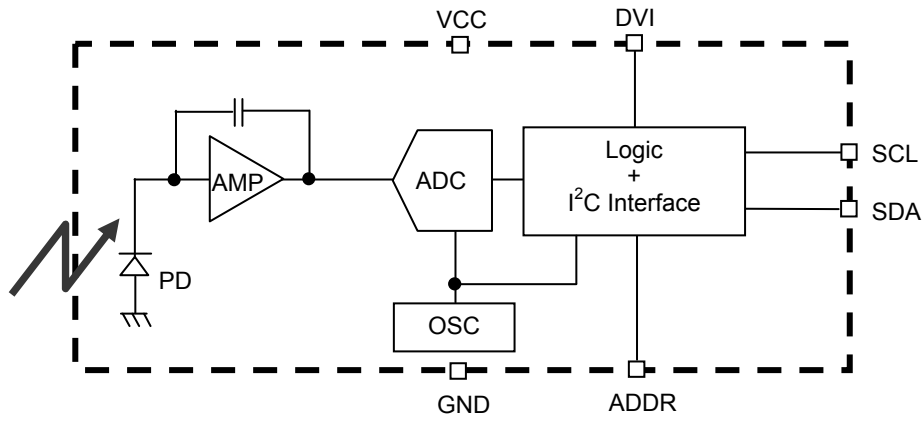


Fig.12 Measurement Result DVI Dependency

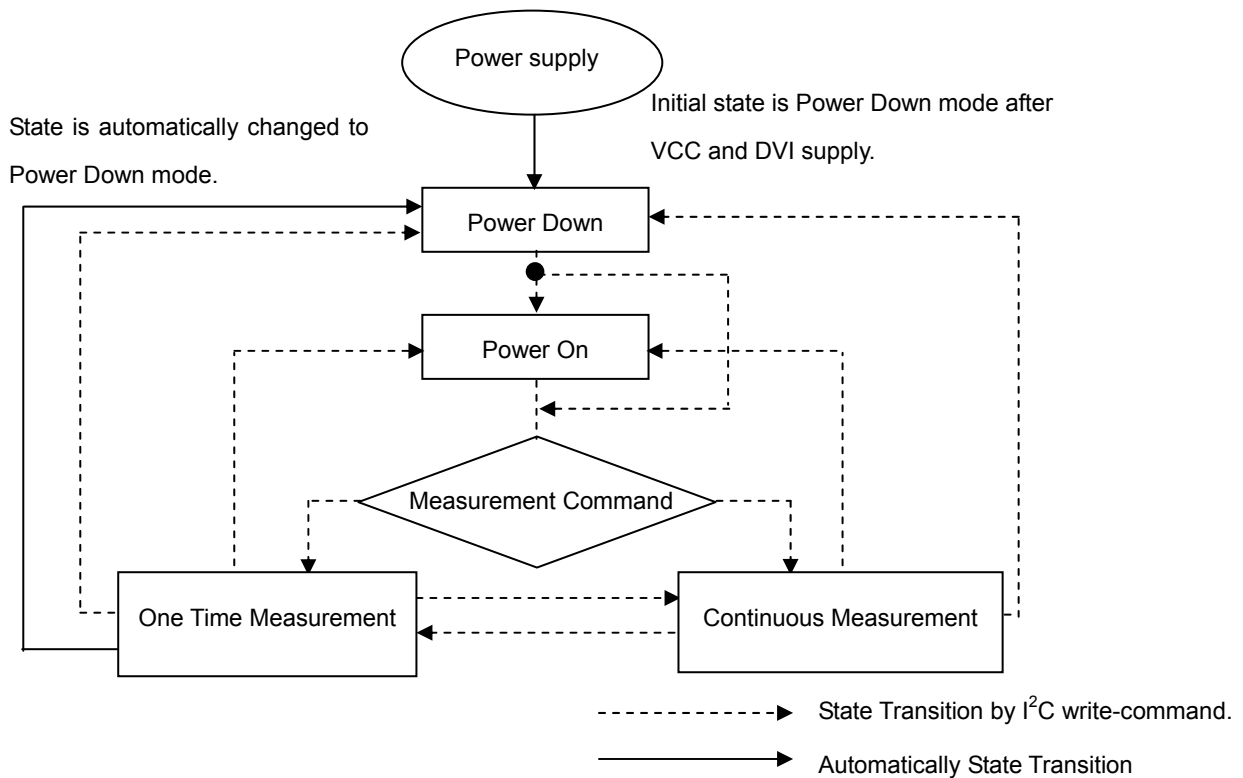
● Block Diagram



● Block Diagram Descriptions

- PD
Photo diode with approximately human eye response.
- AMP
Integration-OPAMP for converting from PD current to Voltage.
- ADC
AD converter for obtainment Digital 16bit data.
- Logic + I²C Interface
Ambient Light Calculation and I²C BUS Interface. It is including below register.
Data Register → This is for registration of Ambient Light Data. Initial Value is "0000_0000_0000_0000".
Measurement Time Register → This is for registration of measurement time. Initial Value is "01_0010_1100".
- OSC
Internal Oscillator (typ. 320kHz). It is CLK for internal logic.

● Measurement Procedure



* "Power On" Command is possible to omit.

● Instruction Set Architecture

Instruction	Opecode	Comments
Power Down	0000_0000	No active state.
Power On	0000_0001	Waiting for measurement command.
Reset	0000_0111	Reset Data register value. Reset command is not acceptable in Power Down mode.
Continuously H-Resolution Mode	0001_0000	Start measurement at 1lx resolution. Measurement Time is typically 120ms.
Continuously M-Resolution Mode	0001_0011	Start measurement at 4lx resolution. Measurement Time is typically 16ms.
Continuously L-Resolution Mode	0001_0110	Start measurement at 32lx resolution. Measurement Time is typically 2.9ms.
One Time H-Resolution Mode	0010_0000	Start measurement at 1lx resolution. Measurement Time is typically 120ms. It is automatically set to Power Down mode after measurement.
One Time M-Resolution Mode	0010_0011	Start measurement at 4lx resolution. Measurement Time is typically 16ms. It is automatically set to Power Down mode after measurement.
One Time L-Resolution Mode	0010_0110	Start measurement at 32lx resolution. Measurement Time is typically 2.9ms. It is automatically set to Power Down mode after measurement.
Change Measurement time (High bit)	010_MT[9,8,7,6,5]	Change measurement time. ※ Please refer "adjust measurement result for influence of optical window."
Change Measurement time (Low bit)	011_MT[4,3,2,1,0]	Change measurement time. ※ Please refer "adjust measurement result for influence of optical window."

※ Don't input the other opecode.

● Measurement mode explanation

Measurement Mode	Measurement Time.	Resolution
H-Resolution Mode	Typ. 120ms.	1 Lx.
M-Resolution Mode	Typ. 16ms.	4 Lx.
L-Resolution Mode	Typ. 2.9ms.	32 Lx.

We recommend to use H-Resolution Mode.

Measurement time (integration time) of H-Resolution Mode is so long that some kind of noise(including in 50Hz / 60Hz noise) is rejected. And H-Resolution Mode is 1 lx resolution so that it is suitable for darkness (less than 10 lx)

● Explanation of Asynchronous reset and Reset command "0000_0111"

1) Asynchronous reset

All registers are reset. It is necessary on power supply sequence. Please refer "Timing chart for VCC and DVI power supply sequence" in this page. It is power down mode during DVI = 'L'.

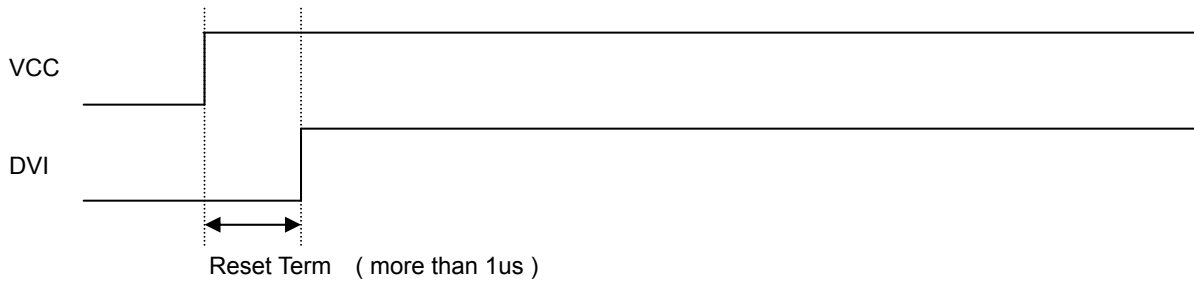
2) Reset command

Reset command is for only reset Illuminance data register. (reset value is '0') It is not necessary even power supply sequence. It is used for removing previous measurement result. This command is not working in power down mode, so that please set the power on mode before input this command.

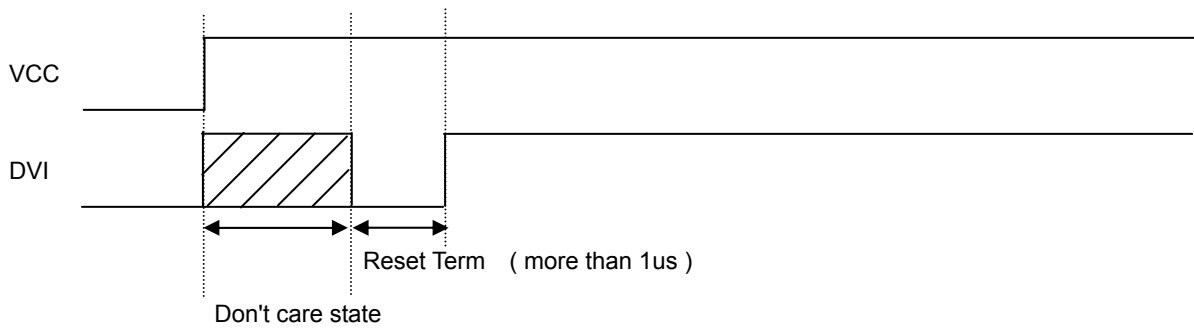
● Timing chart for VCC and DVI power supply sequence

DVI is I²C bus reference voltage terminal. And it is also asynchronous reset terminal. It is necessary to set to 'L' after VCC is supplied. In DVI 'L' term, internal state is set to Power Down mode.

1) Recommended Timing chart1 for VCC and DVI supply.



2) Timing chart2 for VCC and DVI supply.
(If DVI rises within 1us after VCC supply)



ADDR, SDA, SCL is not stable if DVI 'L' term (1us) is not given by systems.

In this case, please connect the resistors (approximately 100kOhm) to ADDR without directly connecting to VCC or GND,

● Measurement sequence example from "Write instruction" to "Read measurement result"

ex1) Continuously H-resolution mode (ADDR = 'L')

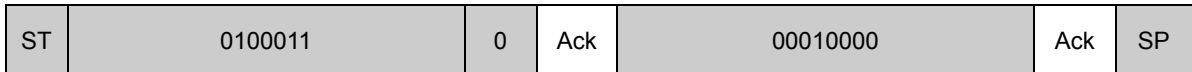


from Master to Slave



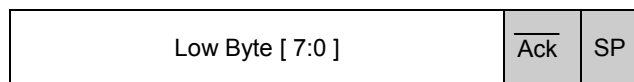
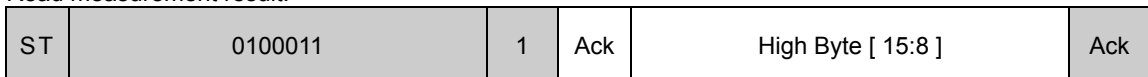
from Slave to Master

① Send "Continuously H-resolution mode " instruction



② Wait to complete 1st H-resolution mode measurement.(max. 180ms.)

③ Read measurement result.

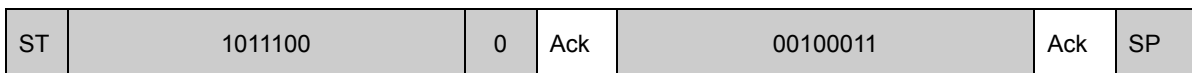


How to calculate when the data High Byte is "10000011" and Low Byte is "10010000"
 $(2^{15} + 2^9 + 2^8 + 2^7 + 2^4) / 1.2 \doteq 28067 [\text{lx}]$

The result of continuously measurement mode is updated.(120ms.typ at H-resolution mode, 16ms.typ at M-resolution mode, 2.9ms.typ at L-resolution mode)

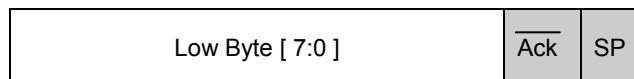
ex2) One time M-resolution mode (ADDR = 'H')

① Send "One time M-resolution mode " instruction



② Wait to complete M-resolution mode measurement.(max. 24ms.)

③ Read measurement result



How to calculate when the data High Byte is "00000001" and Low Byte is "00010000"
 $(2^8 + 2^4) / 1.2 \doteq 227 [\text{lx}]$

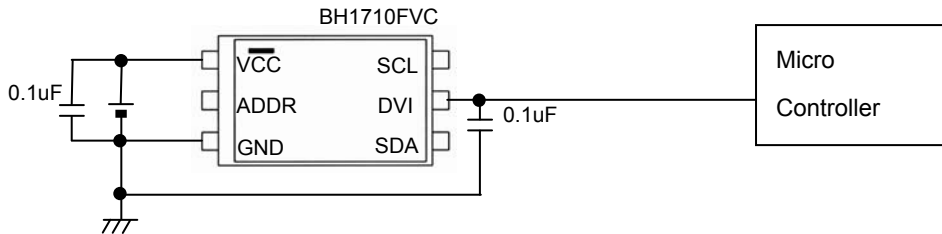
In one time measurement, Statement moves to power down mode after measurement completion. If updated result is need then please resend measurement instruction.

● Application circuit example of DVI terminal

The DVI terminal is an asynchronous reset terminal. Please note that there is a possibility that IC doesn't operate normally if the reset section is not installed after the start-up of VCC. (Please refer to the paragraph of "Timing chart for VCC and DVI power supply sequence")

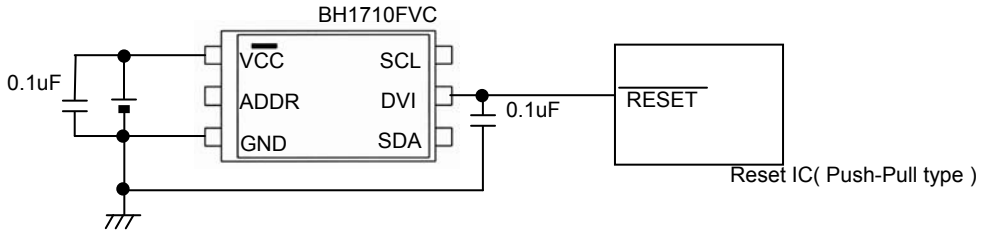
The description concerning SDA and the terminal SCL is omitted in this application circuit example. Please design the application the standard of the I2C bus as it finishes being satisfactory. Moreover, the description concerning the terminal ADDR is omitted. Please refer to the paragraph of "Timing chart for VCC and DVI power supply sequence" about the terminal ADDR design.

ex 1) The control signal line such as CPU is connected.

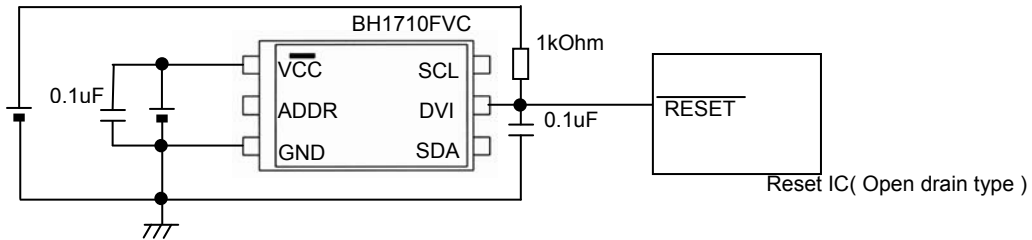


ex 2) Reset IC is used.

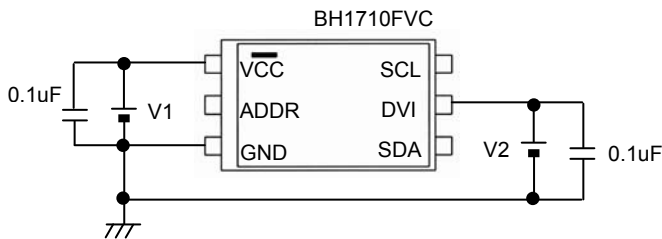
1, For Reset IC of the Push-Pull type



2, For Reset IC of the Open drain output



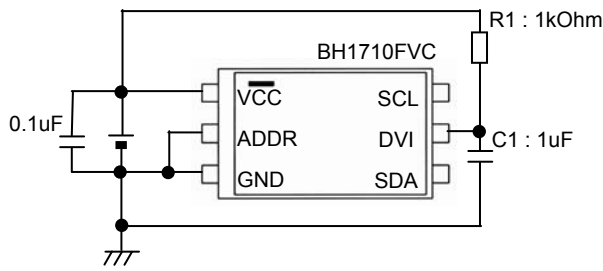
ex 3) A different power supply is used.



※ Power supply of DVI must stand up later than power supply of VCC stand up, because it is necessary to secure reset section (1us or more).

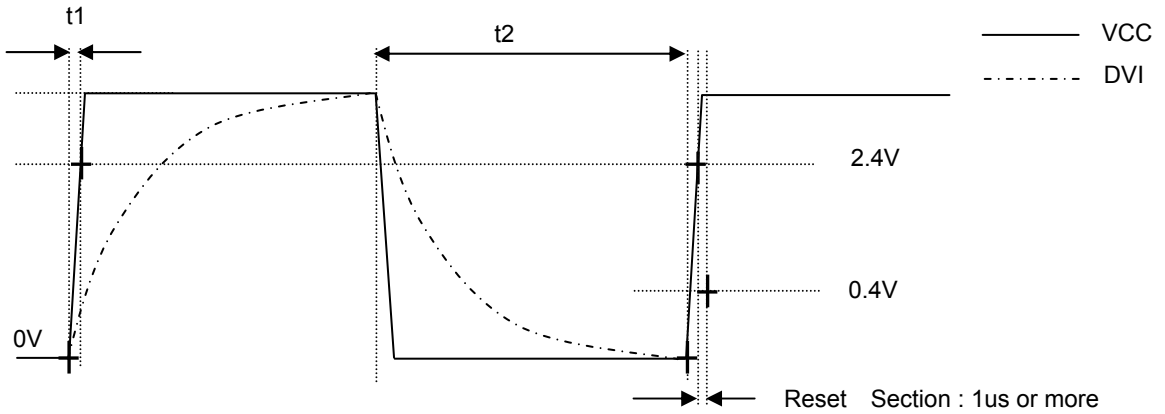
ex 4) LPF using CR is inserted between VCC and DVI.

This method has the possibility that the Reset section of turning on the power supply can not satisfied. cannot be satisfied. Please design the set considering the characteristic of the power supply enough.



◆ Notes when CR is inserted between VCC and DVI

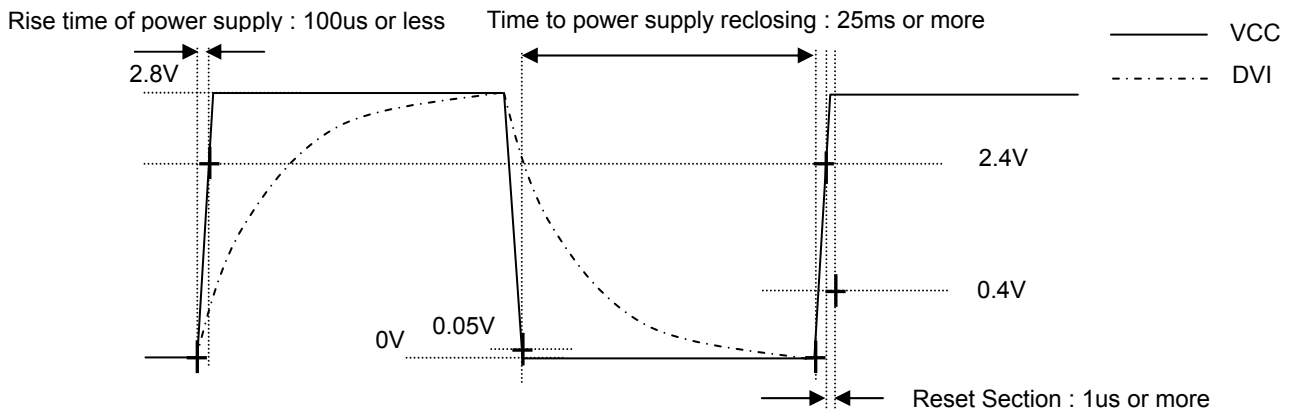
- ※ Please note that there is a possibility that reset section (1us) can not be satisfied because the power supply is turned on when the rise time of VCC is slow
- ※ When VCC is turned off, the DVI voltage becomes higher than VCC voltage but IC destruction is not occurred if recommended constant (R1 = 1kOhm, C1 = 1uF) is used.
- ※ Please note that there is a possibility that Reset section (1usec) cannot be satisfied if wait time is not enough long after turning off VCC.(It is necessary to consider DVI voltage level after turning off VCC.)



• Please do the application design to secure Reset section 1us or more after the reclosing of the power supply.

◆ Example of designing set when CR (C = 1uF, R = 1kΩ) is inserted between VCC and DVI with VCC=2.8V

- ① The rise time to 0→2.4V of VCC must use the power supply of 100us or less.
- ② Please wait 25ms or more after VCC turn off (VCC <= 0.05V), because it is necessary to secure reset section (1us or more).

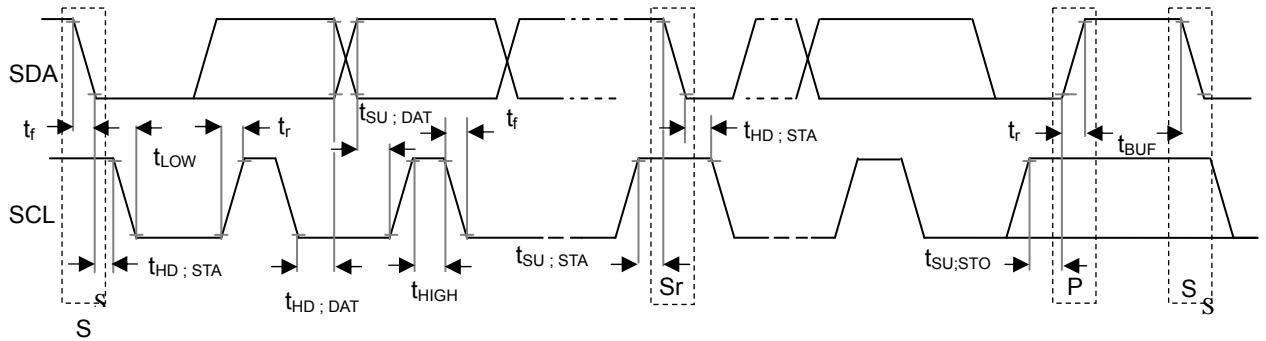


• Please do the application design to secure Reset section 1us or more after the reclosing of the power supply.

● I²C Bus Access

1) I²C Bus Interface Timing chart

Write measurement command and Read measurement result are done by I²C Bus interface. Please refer the formally specification of I²C Bus interface, and follow the formally timing chart.



2) Slave Address

Slave Address is 2 types, it is determined by ADDR Terminal

ADDR = 'H' (ADDR \geq 0.7VCC) \rightarrow "1011100"

ADDR = 'L' (ADDR \leq 0.3VCC) \rightarrow "0100011"

3) Write Format

BH1710FVC is not able to accept plural command without stop condition. Please insert SP every 1 Opecode.

ST	Slave Address	R/W 0	Ack	Opecode	Ack	SP
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4) Read Format

ST	Slave Address	R/W 1	Ack	High Byte [15:8] $2^{15} \ 2^{14} \ 2^{13} \ 2^{12} \ 2^{11} \ 2^{10} \ 2^9 \ 2^8$	Ack
				Low Byte [7:0] $2^7 \ 2^6 \ 2^5 \ 2^4 \ 2^3 \ 2^2 \ 2^1 \ 2^0$	$\overline{\text{Ack}}$ SP



from Master to Slave



from Slave to Master

ex)

High Byte = "1000_0011"

Low Byte = "1001_0000"

$$(2^{15} + 2^9 + 2^8 + 2^7 + 2^4) / 1.2 \doteq 28067 [\text{lx}] \quad \ast_2$$

* I²C BUS is trademark of Phillipps Semiconductors. Please refer formality specification.

● Adjust measurement result for influence of optical window.

BH1710FVC is including in adjust measurement result function for influence of optical window. Adjust is done by changing measurement time. For example, if transmission rate by optical window is 1 / N, then adjust is done by measurement time is set to "initial value * N".

Measurement time register (Mtreg) is 10bit register. Initial value is "01_0010_1100" (12Cxh). Please change this register value via to I²C Bus interface.

ex) Case of transmission rate is 50%.

Please change Mtreg value from "01_0010_1100" to "10_0101_1000".

1) Changing High bit of Mtreg

ST	Slave Address	R/W 0	Ack	010_10010	Ack	SP
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2) Changing Low bit of Mtreg

ST	Slave Address	R/W 0	Ack	011_11000	Ack	SP
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3) Input Measurement Command.

ST	Slave Address	R/W 0	Ack	0001_0000	Ack	SP
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※ This example is High Resolution mode, but it accepts the other measurement.

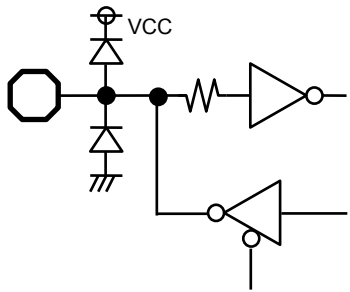
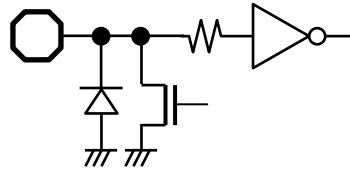
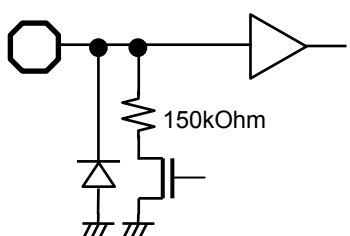
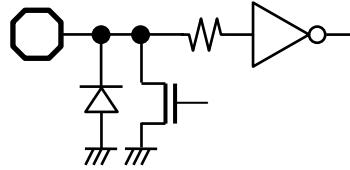
4) After about 240ms, measurement result is registered to Data Register. (High Resolution mode is typically 120ms, but measurement time is set twice.)

Supported Mtreg value is seeing below.

	Min.	Typ.	Max
Supported value (hex)	00110_00100 (transmission rate 153%)	01001_01100 (transmission rate 100%)	11111_11110 (transmission rate 29.4%)

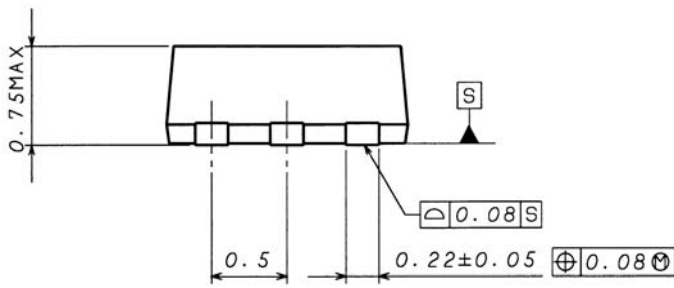
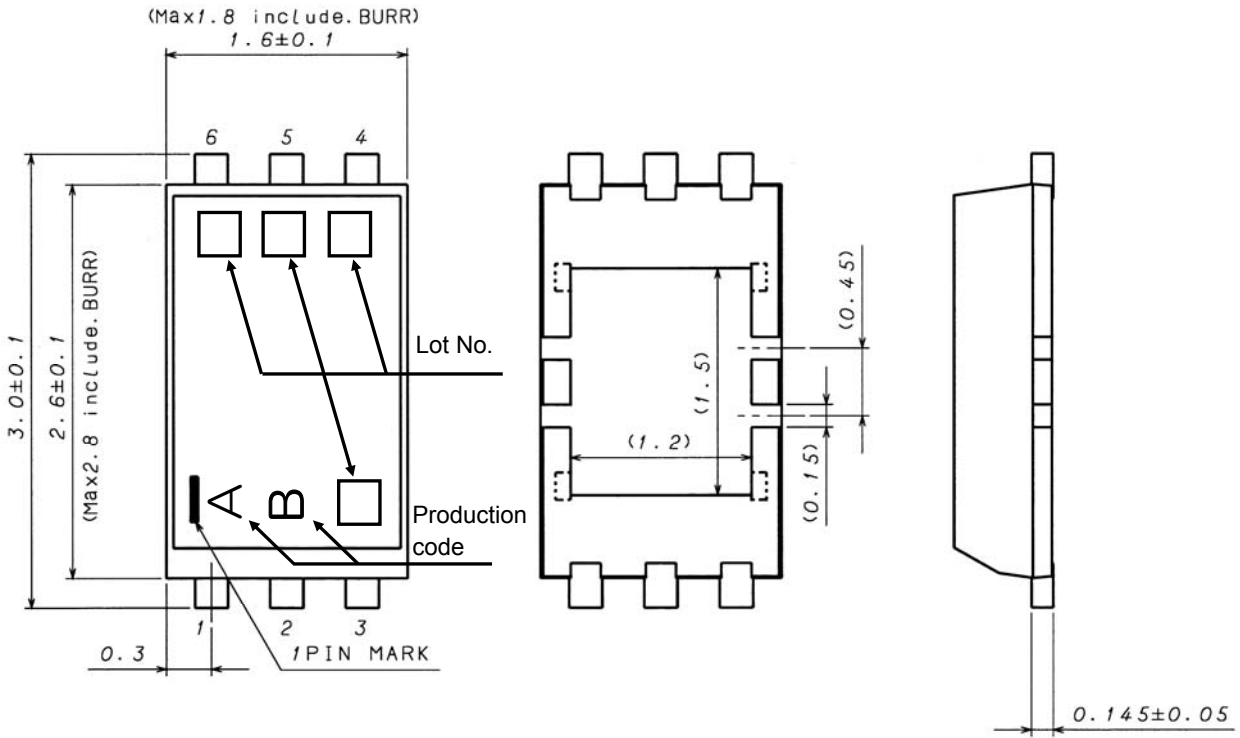
For example BH1710FVC is possible to detect min. 0.35 lx when Mtreg value is "11111_11110" at H-Resolution mode.

● Terminal Description

PIN No.	Terminal Name	Equivalent Circuit	Function
1	VCC		Power Supply Terminal
2	ADDR		<p>I²C Slave-address Terminal</p> <p>ADDR = 'H' (ADDR \geq 0.7VCC) "1011100" ADDR = 'L' (ADDR \leq 0.3VCC) "0100011" ADDR Terminal is designed as 3 state buffer for internal test. So that please take care of VCC and DVI supply procedure. Please see P6.</p>
3	GND		GND Terminal
4	SDA		I ² C bus Interface SDA Terminal
5	DVI		<p>SDA, SCL Reference Voltage Terminal</p> <p>And DVI Terminal is also asynchronous Reset for internal registers. So that please set to 'L' (at least 1us, DVI \leq 0.4V) after VCC is supplied. BH1710FVC is pulled down by 150kOhm while DVI = 'L'.</p>
6	SCL		I ² C bus Interface SCL Terminal

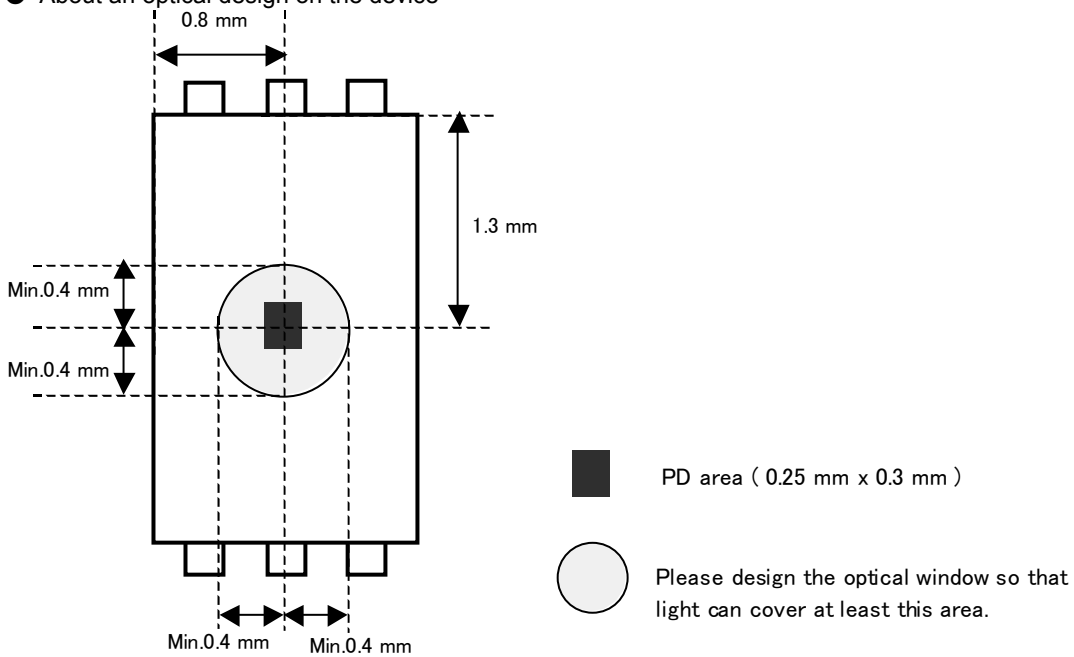
※ These values are design-value, not guaranteed.

● Package Outlines



WSOF6 (Unit : mm)

● About an optical design on the device



●Cautions on use

1) Absolute Maximum Ratings

An excess in the absolute maximum ratings, such as supply voltage (V_{max}), temperature range of operating conditions (T_{opr}), etc., can break down devices, thus making impossible to identify breaking mode such as a short circuit or an open circuit. If any special mode exceeding the absolute maximum ratings is assumed, consideration should be given to take physical safety measures including the use of fuses, etc.

2) GND voltage

Make setting of the potential of the GND terminal so that it will be maintained at the minimum in any operating state. Furthermore, check to be sure no terminals are at a potential lower than the GND voltage including an actual electric transient.

3) Short circuit between terminals and erroneous mounting

In order to mount ICs on a set PCB, pay thorough attention to the direction and offset of the ICs. Erroneous mounting can break down the ICs. Furthermore, if a short circuit occurs due to foreign matters entering between terminals or between the terminal and the power supply or the GND terminal, the ICs can break down.

4) Operation in strong electromagnetic field

Be noted that using ICs in the strong electromagnetic field can malfunction them.

5) Inspection with set PCB

On the inspection with the set PCB, if a capacitor is connected to a low-impedance IC terminal, the IC can suffer stress. Therefore, be sure to discharge from the set PCB by each process. Furthermore, in order to mount or dismount the set PCB to/from the jig for the inspection process, be sure to turn OFF the power supply and then mount the set PCB to the jig. After the completion of the inspection, be sure to turn OFF the power supply and then dismount it from the jig. In addition, for protection against static electricity, establish a ground for the assembly process and pay thorough attention to the transportation and the storage of the set PCB.

6) Input terminals

In terms of the construction of IC, parasitic elements are inevitably formed in relation to potential. The operation of the parasitic element can cause interference with circuit operation, thus resulting in a malfunction and then breakdown of the input terminal. Therefore, pay thorough attention not to handle the input terminals; such as to apply to the input terminals a voltage lower than the GND respectively, so that any parasitic element will operate. Furthermore, do not apply a voltage to the input terminals when no power supply voltage is applied to the IC. In addition, even if the power supply voltage is applied, apply to the input terminals a voltage lower than the power supply voltage or within the guaranteed value of electrical characteristics.

7) Thermal design

Perform thermal design in which there are adequate margins by taking into account the power dissipation (P_d) in actual states of use.

8) Treatment of package

Dusts or scratch on the photo detector may affect the optical characteristics. Please handle it with care.

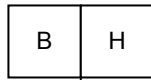
9) Rush current

When power is first supplied to the CMOS IC, it is possible that the internal logic may be unstable and rush current may flow instantaneously. Therefore, give special consideration to power coupling capacitance, power wiring, width of GND wiring, and routing of connections.

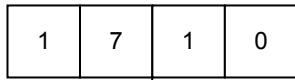
10) The exposed central pad on the back side of the package

There is an exposed central pad on the back side of the package. But please do it non connection. (Don't solder, and don't do electrical connection) Please mount by Footprint dimensions described in the Jisso Information for WSOF6. This pad is GND level, therefore there is a possibility that LSI malfunctions and heavy-current is generated.

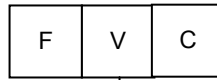
●Product Designations (Selecting a model name when ordering)



Rohm Model



Part number

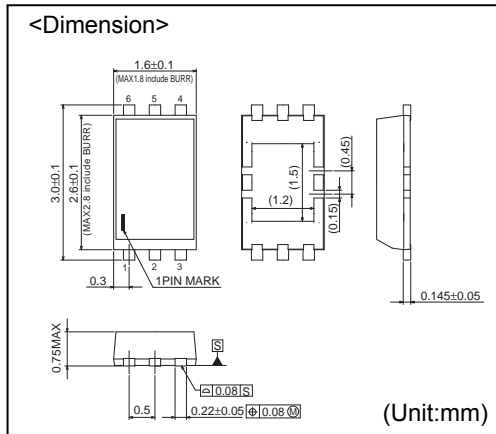


Package type



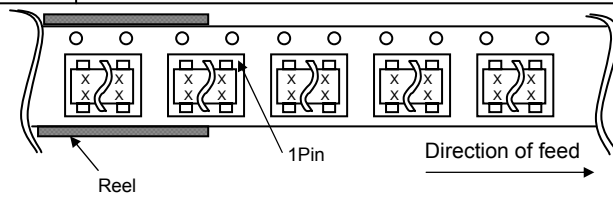
TR = Reel-wound embossed taping

WSOF6



<Tape and Reel information>

Tape	Embossed carrier tape
Quantity	3000pcs
Direction of feed	TR (The direction is the 1pin of product is at the upper light when you hold reel on the left hand and you pull out the tape on the right hand)



※When you order , please order in times the amount of package quantity.

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